COGNEX

IN-SIGHT 2D ROBOT GUIDANCE FOR UNIVERSAL ROBOTS

The Cognex[®] In-Sight[®] 2D Robot Guidance URCap plugin greatly simplifies the communication, hand-eye calibration, and vision-guided robotics development between a UR robot and a Cognex 2D vision system.

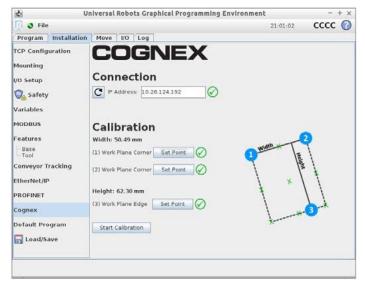
The plugin takes advantage of Cognex's world class vision tools for any robot application. The system can be used to guide the robot to specific coordinates, inspect the part after manipulation, and output valuable data for downstream analysis.

Benefits at a glance

- Greatly simplifies two of the main challenges in vision guided robotics:
 - 1. Establishing communication between the systems
 - 2. Performing the hand-eye calibration
- Intuitive URCap interface guides users through the procedure.
- ➤ Fully integrated into Cognex In-Sight Explorer[™] software, providing access to the industry's most powerful and robust vision tools.
- Compatible with any spreadsheet-enabled In-Sight vision system.



UNIVERSAL ROBOTS 🕂





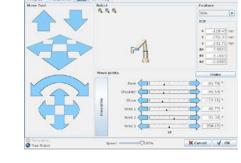
How it works

1. Establish communication

The URCap interface provides feedback when the vision system and robot have successfully established communication.

2. Perform hand-eye calibration

The interface guides the user through the steps required for a hand-eye calibration between the robot and the vision system.



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3. Train camera pose for pick/place operation

Once a calibration file has been produced, the Cognex Camera Pose command in the URCap software programs the robot to perform a vision-guided movement.

Basic	Advanced	Wizards	URCaps
Co	gnex Camera	a Pose	

Resources

Get started by downloading the URCap software* and In-Sight/URCap user manual www.cognex.com/URCap

Learn more about the Cognex In-Sight 2D Robot Guidance on UR+ Solutions

www.universal-robots.com/plus/accessories/cognex-in-sight-2d-robot-guidance

* Compatible with In-Sight Explorer 5.7 and greater



Companies around the world rely on Cognex vision and barcode reading solutions to optimize quality, drive down costs and control traceability.

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